

Parametric resonances in periodically perturbed dynamo models

André Giesecke & Frank Stefani Helmholtz-Zentrum Dresden-Rossendorf

Workshop Freiburg, May 7th - 9th 2018

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Dynamo action and cosmic magnetic fields



- cosmic magnetic fields can be observed on all scales: asteroids, moons, planets, stars, galaxies, ...
- magnetic field generation process:
 homogenous dynamo: transfer of kinetic energy of a flow of a conductive fluid into magnetic energy
 numerical, theoretical and experimental studies on fluid flow driven magnetic field generation
- this talk: focus on experimental dynamo action, but motivation also by natural systems
- response of system with impact by external periodic perturbation
- dynamo efficiency (growth rate, threshold), phase

Fluid Flow Driven Dynamo Experiments



- complex problem because induced currents do not flow along fixed path (like in technical dynamo) but are determined by the nature of the induced electromotive force $\mathcal{E} \propto \mathbf{\mu} \times \mathbf{B}$
- three successful experiments with fluid flow driven dynamo action



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Example: Von-Kármán-Sodium (VKS) dynamo





- flow of liquid sodium driven by two counterrotating impellers
- mean flow structure: two poloidal cells, two toroidal cells (S2T2)
- dynamo at $\mathrm{Rm}^{\mathrm{c}} = \mathcal{U}_{\mathrm{max}} R / \eta \approx 32$ but soft iron impellers $\mu_{\mathrm{r}} \approx 65$



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Flow model for the VKS dynamo



water experiment at Universidad de Navarra (Pamplona) used for estimation of flow properties







turbulent flow in water experiment mean axisymmetric flow non-axisymmetric m = 2 perturbation



 impact of non-axisymmetric perturbations on dynamo action driven by a large scale axisymmetric flow

 \Rightarrow beneficial or obstructive

- possible realisation in natural or experimental dynamos
 - convection driven dynamos with impact from tidal forcing (m = 2) or precession (m = 1)
 - azimuthally drifting vortices in cylindrical flow with von-Kármán like driving (Giesecke et al. PRE 2012)
 - 'swing-excitation' caused by density waves in spiraling galaxies (Chiba & Tosa, MNRAS 2002)
- synchronization of dynamo cycles with external impact of periodic distortion (Stefani et al, Solar Physics 2016)



induction equation

$$\frac{\partial}{\partial t} \mathbf{B} = \nabla \times (\mathbf{u} \times \mathbf{B} - \eta \nabla \times \mathbf{B})$$

$$\mathbf{B} \sim \mathbf{B}_0(\mathbf{r}) e^{\lambda t} \Rightarrow \lambda \mathbf{B} = \mathcal{M} \mathbf{B}$$

prescribed velocity field u(r, t)

• linear problem
$$\Rightarrow$$
 eigenvalues λ

no magnetic backreaction

Two different approaches for solution

(1) timestepping with hybrid Finite Volume/Boundary Element Method \Rightarrow calculation of eigenvalues $\Rightarrow \lambda = \gamma + i\omega$ with growth rates γ and frequencies ω

(2) simple analytic model for field amplitude

 \Rightarrow periodic velocity perturbation $\mathbf{u} = \mathbf{u}_0^{\mathrm{axi}} + \epsilon \mathbf{u}_1^{\mathrm{nonaxi}}(t)$

⇒ Floquet-theorem: $\mathbf{B} \sim P(t)e^{Rt}$ with P(t) same periode as perturbation and constant matrix R

Simplified velocity model

- Beltrami like flow $\nabla \times \mathbf{u} \propto \mathbf{u}$ \Rightarrow helicity maximizing \Rightarrow well suited for dynamo action
- meridional flow: $\mathbf{u} = \nabla \times \Psi$ with $\Psi = J_1(\alpha r) \sin\left(\frac{2\pi z}{\mu}\right) \hat{\mathbf{e}}_{\omega}$
- toroidial flow is given by $u_{\varphi} = -\sqrt{\alpha^2 + \left(\frac{2\pi}{H}\right)^2} J_1(\alpha r) \sin\left(\frac{2\pi z}{H}\right)$
- \blacksquare J₁ cylindrical Bessel function $\alpha = 3.8317$ (first zero of J_1) $\Rightarrow \nabla \times \mathbf{u} = -\sqrt{\alpha^2 + (\frac{n\pi}{H})^2 \mathbf{u}}$
- flow consists of 2 toroidal flow cells with different orientation and 2 recirculating cells in the meridional plane (somehow related to the mean flow in the VKS dynamo)









Modelling the velocity perturbation



$\mathbf{u}'(\mathbf{r},t) = \nabla \times \mathbf{A}\cos(m(\varphi+\omega)t)$ with $\mathbf{A} = V_a r [\cos(2\pi r) - 1]\cos(2\pi z) \hat{\mathbf{e}}_z$



vortex-like structure along the axis with azimuthal wavenumber m = 2
 azimuthal propagation of perturbation with drift frequency ω

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Numerical Results: temporal evolution of **B**





- temporal behavior of magnetic eigenmode depends on azimuthal drift of the non-axisymmetric perturbation
- "fast" drift \Rightarrow decaying solution with amplitude modulation
- \blacksquare "slow drift" \Rightarrow growing solution and no amplitude modulation

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Visualization of the behavior





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Growth rates and frequencies





Coalescence of Eigenmodes

- \blacksquare merging of eigenmodes \Rightarrow parametric resonance for $|\omega| \lesssim 2\omega_0$
- exceptional points (degeneration of eigenvalues and eigenfunctions)
- frequency locking within resonant regime
- similar to mechanical systems subject to periodic distortions

Analogy with periodically perturbed oscillator



Matthieu Equation: $\ddot{Q} + \omega^2(t)Q = 0$ with $\omega(t) = \omega_0(1 + \epsilon \cos(\tilde{\omega}t))$



⇒ growthrates in resonant regime: $\gamma = \pm \sqrt{(\epsilon \omega_0)^2 - (\tilde{\omega} - 2\omega_0)^2}$ outside resonance: $\omega = 0.5\tilde{\omega} \pm \sqrt{(\tilde{\omega} - 2\omega_0)^2 - (\epsilon \omega_0)^2}$

 \Rightarrow within resonant regime solution locks to perturbation frequency $\omega\!=\!\widetilde{\omega}$

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Reduction of threshold





"asymptotic" behavior for increasing perturabtion amplitude

- \blacksquare reduction from ${\rm Rm^c}=39$ to ${\rm Rm^c}=26$
- optimum depends on azimuthal drift of unperturbed eigenmode (here strongest reduction for "standing" vortices with $\omega = 0$)

More complex solutions possible...



non-drifting basic state but amplitude modulation of magnetic field



- \blacksquare sharp peaks for $\Omega_{\rm p}\approx 2\Omega_0 \Rightarrow$ parametric resonance
- location of maximum depends on amplitude of perturbation
- broader peaks for larger frequencies (but no resonance)

Temporal behavior of magnetic eigenmode







Low dimensional model



- assume axisymmetric flow U₀ and a non-axisymmetric periodic perturbation with azimuthal wave number m̃ and frequency ω
 U(r, t)=U₀(r, z) + ε [u_{m̃}(r, z)e^{i(m̃φ+ωt)} + u_{-m̃}(r, z)e^{-i(m̃φ+ωt)}]
- reduction of induction equation into a system of equations for the amplitude of azimuthal field modes

$$\mathbf{B} = \sum_{-M}^{M} \hat{b}_m(t) \mathbf{b}_m(r,z) e^{im\varphi}$$

Assumptions

modes are modulated by simple temporal varying amplitude

 consider only leading eigenmode for each azimuthal wave number (i.e. only one single mode is close to be unstable)

but linear operator in induction equation is non-normal \Rightarrow in general these assumptions are not correct

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Floquet approach





- diagonal elements: $\alpha_{j,j}$ are the growth rates of the unperturbed case
- off-diagonal parameters $\alpha_{m,m\pm 2} \Rightarrow$ interaction of adjacent modes

• time dependence:
$$f_t = \epsilon e^{i\omega t}$$

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Floquet approach



- (1) solution of $\frac{d}{dt}B(t) = A(t)B(t)$ with a *T*-periodic matrix A(t)=A(t+T)and a *n*-dimensional vector *B* is given by $B(t) = P(t)e^{Rt}$ with a *T*-periodic invertible matrix P(t) = P(t+T) and a constant matrix *R*
- (2) it is always possible to find a transformation B(t) = P(t)X(t) such that $\frac{d}{dt}X(t) = RX(t)$ and $R = e^{-iDt}Ae^{iDt} iD$ is constant
- (3) in our particular case we can write $A(t) = e^{iD_{\omega}t} \hat{A}e^{-iD_{\omega}t}$ with \hat{A} the matrix A without time modulation $e^{\pm i\omega t}$ and

$$D_{\omega} = \begin{pmatrix} -\frac{M}{2}\omega & 0 & & & \\ 0 & -\frac{M-2}{2}\omega & 0 & & \\ & 0 & \ddots & 0 & \\ & & 0 & \frac{M-2}{2}\omega & 0 \\ & & & 0 & \frac{M-2}{2}\omega \end{pmatrix}$$

 $\Rightarrow R = \hat{A} - iD_{\omega}$ so that $\frac{dX}{dt} = (\hat{A} - iD_{\omega})X$ with solutions $X = X_0 e^{\tilde{\sigma}t}$

 \Rightarrow eigenvalues $\tilde{\sigma}$ are roots of characteristic equation $|\hat{A} - iD_{\omega} - \tilde{\sigma}\mathbb{I}| = 0$

Example: Truncation at M = 1



$$\begin{pmatrix} \frac{d}{dt}\hat{b}_{-1} \\ \frac{d}{dt}\hat{b}_{1} \end{pmatrix} = \begin{pmatrix} \alpha^{*} & \epsilon e^{-i\omega t}\gamma^{*} \\ \epsilon e^{i\omega t}\gamma & \alpha \end{pmatrix} \begin{pmatrix} \hat{b}_{-1} \\ \hat{b}_{1} \end{pmatrix} \Rightarrow \qquad \hat{A} = \begin{pmatrix} \alpha^{*} & \epsilon\gamma^{*} \\ \epsilon\gamma & \alpha \end{pmatrix} \begin{pmatrix} \hat{b}_{-1} \\ \hat{b}_{1} \end{pmatrix} \Rightarrow \qquad D_{\omega} = \begin{pmatrix} -\omega/2 & 0 \\ 0 & \omega/2 \end{pmatrix}$$

characteristic equation

$$\left(\alpha^* + i\frac{\omega}{2} - \widetilde{\sigma}\right)\left(\alpha - i\frac{\omega}{2} - \widetilde{\sigma}\right) - \epsilon^2 |\gamma|^2 = 0 \Rightarrow \widetilde{\sigma}_{\pm} = \alpha_r \pm \frac{1}{2}\sqrt{4\epsilon^2 |\gamma|^2 - (2\alpha_i - \omega)^2}$$



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Perturbed system





models become more complex for higher truncation order

- interaction m = 1 and $m = -1 \Rightarrow$ parametric resonance
 - interaction m = 1 and $m = 3 \Rightarrow$ amplification, no frequency locking

Perturbed system





■ incvreasing order of truncation (M = 1, 3, 5) leads to increasing complexity ⇒ coupling must decrease for convergence of model



Summary, Conclusions & Outlook



- external perturbation may have a significant impact on dynamo action driven by a large scale axisymmetric flow
- mechanism: coupling of different eigemodes ⇒ enhancement of dynamo efficiency
- complex dependence on frequency and amplitude
- Natural example: precession driven flows in case of a triadic resonance of inertial modes but realization not very probable
- frequency locking occurs in case of parametric resonance but amplificatin/enhancement of growth rates possible without synchronization
- frequency locking requires $\Omega_p = 2\Omega_0$, i.e. adoption of external perturbation frequency to internal frequency of system \Rightarrow different from non-linear synchronization in dynamo model presented by Frank